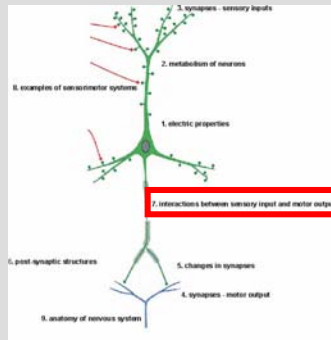


7. interactions between sensory input and motor output

script will be available by FTP from
IP address: 134.2.99.9
user: guenne03



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1

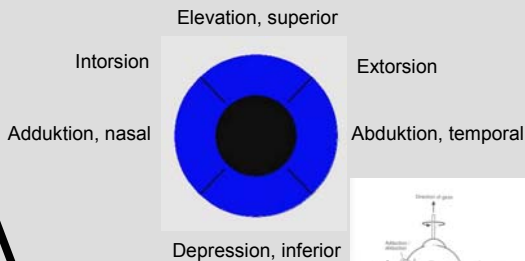
eye movements:
example for sensorimotor integration

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2

frame of references

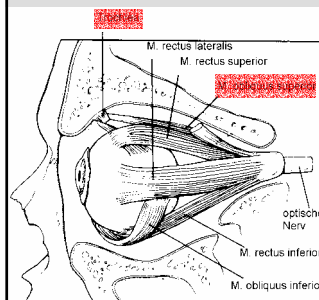


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extraocular muscles



Nerve	Muscle	Action
III	rectus superior	Elevation
III	obliquus inferior	Elevation
III	rectus inferior	Depression
IV	obliquus superior	Depression
VI	rectus lateralis	Abduktion
III	rectus medialis	Adduktion

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extraocular muscles have to compensate:

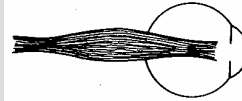
~~gravity (not relevant)~~

friction (constant)

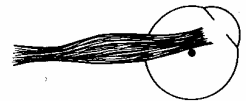
viscosity (dx/dt)

inertia (d^2x/dt^2)

action of muscle depends on eye position



(a)



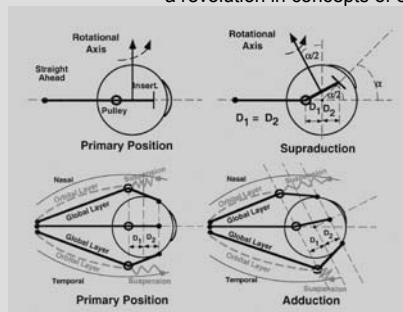
(b)

backup extra-ocular muscles

6 muscles, 3 orthogonal rotation axis

no monosynaptic reflex

**The orbital pulley system:
a revolution in concepts of orbital anatomy**



tracking the eye position

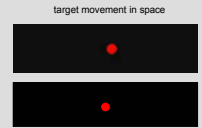
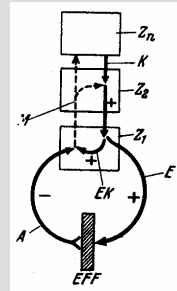
methode	advantage	disadvantage
EOG (Elektro-Okulograph)	simple comfortable cheap	not precise, high drifts
IROG (infrarot-Okulograph)	non-invasive cheap	bad vertical signal narrow range
VOG (Video-Okulograph)	precise 3D	slow expensive
Coils (magnetic induction)	precise huge range 3D	invasive

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example: visual motion perception



retinal image movement

Perception?

centre Z_1 gives efferent (E) information to effector (EFF) and receives afferent information (A)

higher centres Z_2 to Z_n
internal command (K) causes efferent impulses (E) and
reafferent signals (A -)
simultaneously, efference copy (EK) is transmitted

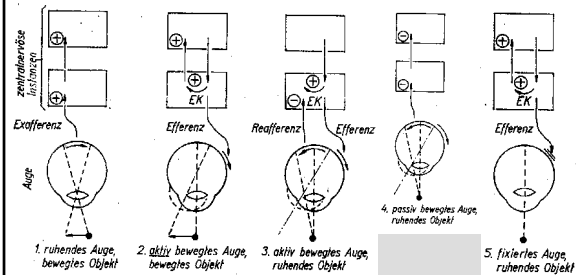
my own scientific interest

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Reafferenz-Prinzip



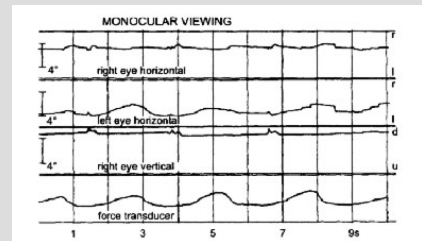
Alles da

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passive movement: different in monocular viewing conditions



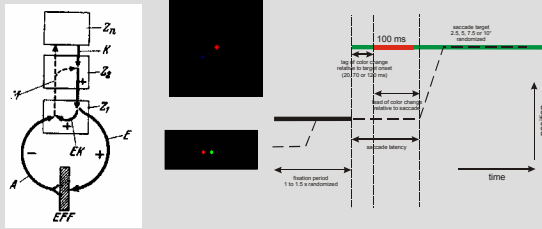
- pressed eye remains stationary (OKR)
- eye muscle compensates for finger force
- Hering's Law: conjugate eye movements
- occluded eye moves nasally
- perception of apparent motion is due to efference copy

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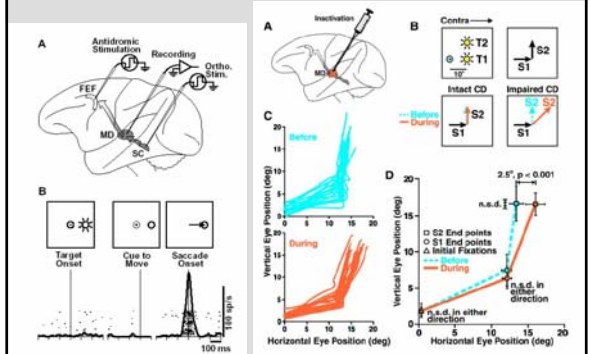
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Problem: time difference between efference copy and reafferent signal (=sum of motor and sensory delay)



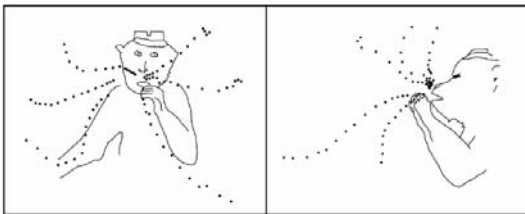
efference copy (or corollary discharge) present in thalamus



Sommer & Wurtz (2002) A pathway in primate brain for internal monitoring of movements

motor cortex (MI)

brief stimulation trains: twitches in muscles depending of homunculus
long stimulation trains: yields complex movement pattern



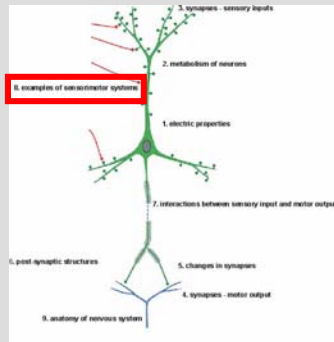
MI must know the present position of the hand!

Graziano et al (2002) Complex Movements Evoked by Microstimulation of Precentral Cortex

Summary:

- ideal system for sensorimotor integration: eye movements
- six extraocular muscles
- reaffrence principle: sensory signals are combined with an internal copy of the motor command
- Thalamus might transmit efference copy from SC to FEF
- MI receives input related to the actual posture

8. examples of sensorimotor systems



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1. visual system of primates

2. whisker system in seals

see Guido Dehnhardt, Ruhr-Uni Bochum,
Zoo at Köln

explain seal vs submarine

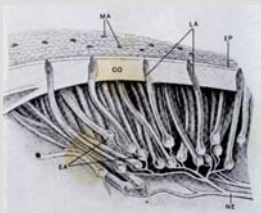
3. electric sense

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Lorenz' ampullae in sharks (rostrum)



black dots: openings of LA
open circles: sensors of lateral line organ
black line: lateral line organ

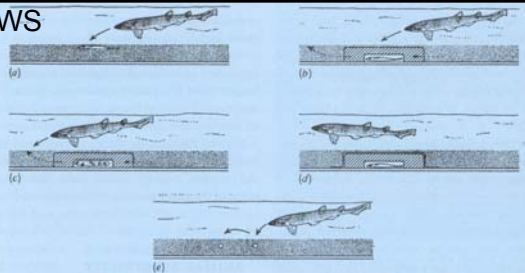
CO corium
EA end of ampulla
EP epidermis
LA Lorenz' ampulla
MA opening of ampulla
NE nerve

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JAWS



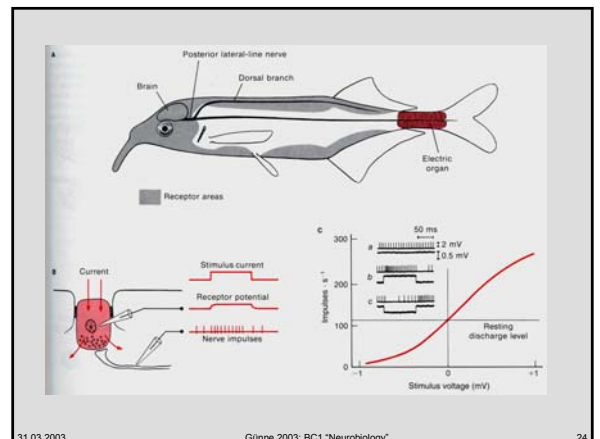
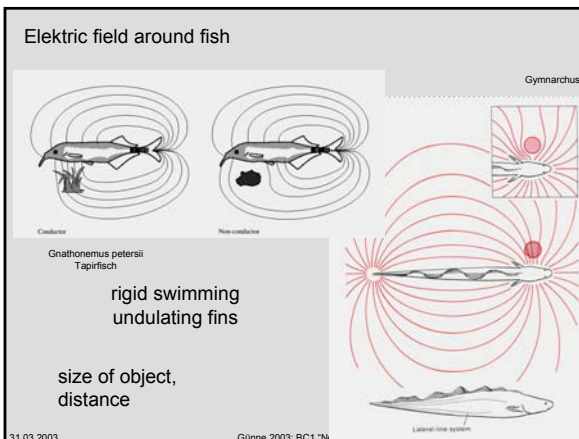
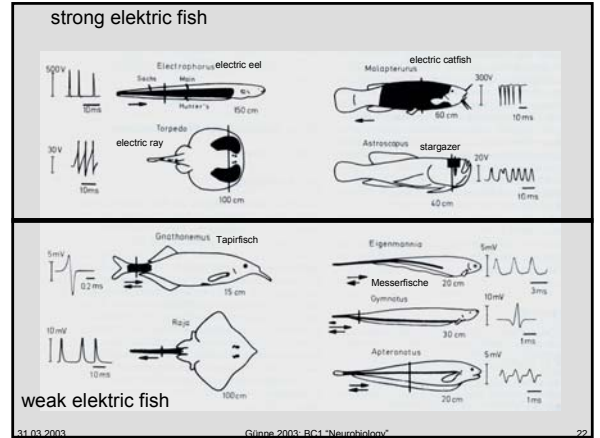
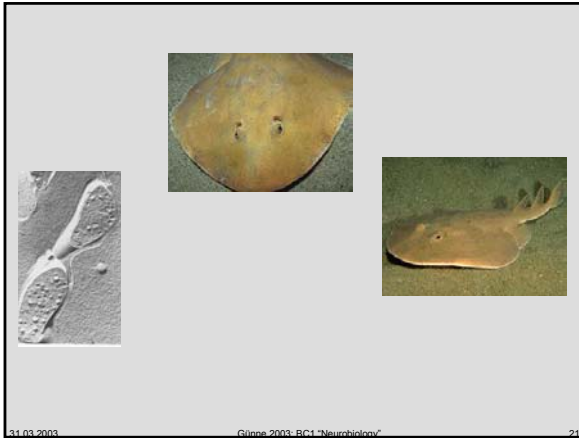
a) hungry shark and flounder (positive)
b) flounder below agar roof (positive)
c) pieces of fish below agar roof
(attack is directed towards the end of roof)
d) flounder below agar roof and isolator (negative)
e) artificial electric field (positive)

positive = shark reacts

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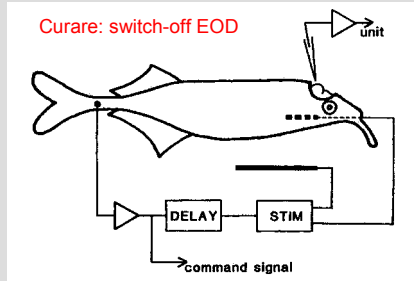
20



Experiment:

PLLL: posterior lateral line lobe

Curare: switch-off EOD



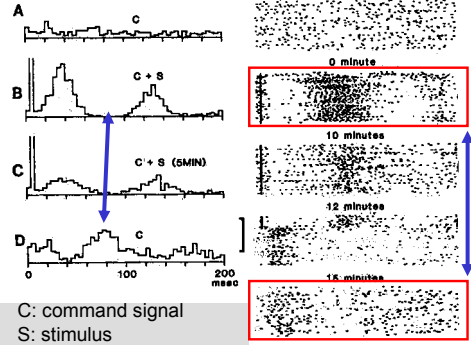
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peri-stimulus time histograms PSTH

Raster display



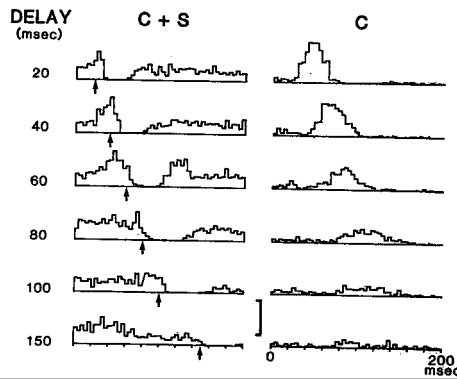
interpretation: adaptive efference copy

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specific for delay

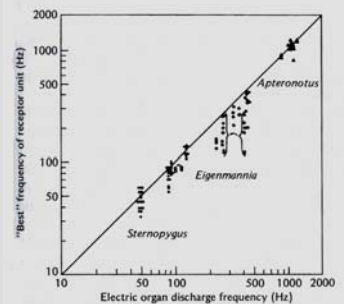


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more examples for SENSORIMOTOR INTEGRATION

best frequencies
of
EOD electric organ discharge
and
receptors

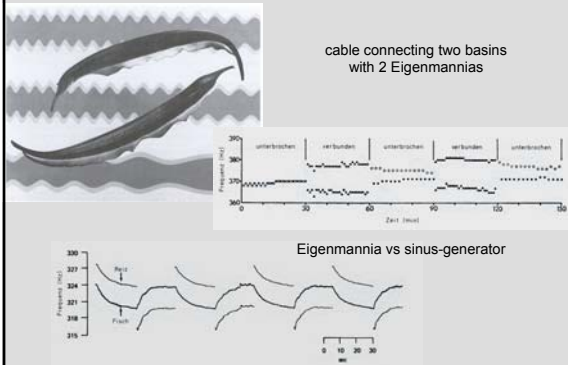


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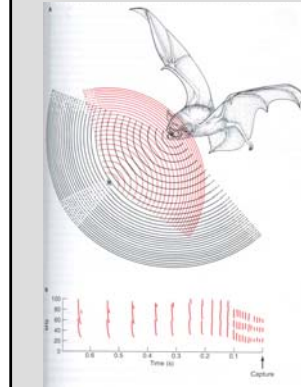
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2. Jamming Avoidance Response JAR



echo-localization in bats



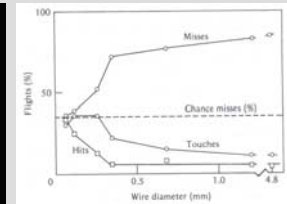
Myotis lucifugus
FM bat

performance of bat:

- detection of (reflected) echo
- determine the distance
- determine the direction
- determine properties of object

behaviour

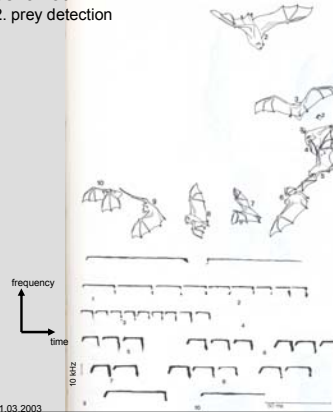
1. detection of obstacles



Myotis lucifugus
vertical wires 30 cm spacing

behaviour

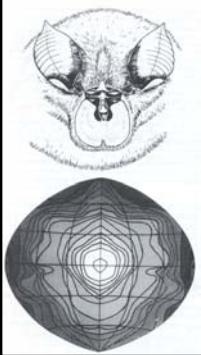
2. prey detection



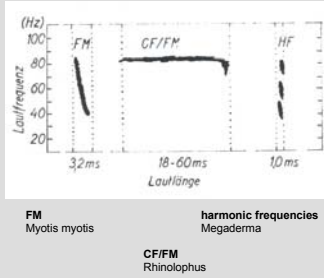
hunting *Rhinolophus*

- 1: CF 82 kHz, FM sweep at on- and offset
- 4: butterfly caught, no vocalisation

horseshoe bat:
tuning of vocalization



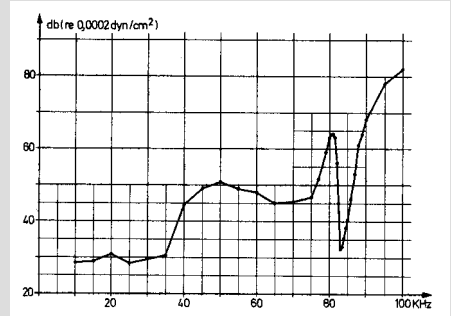
different localisation calls



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auditory fovea in CF bats
audiogram (IC recordings)



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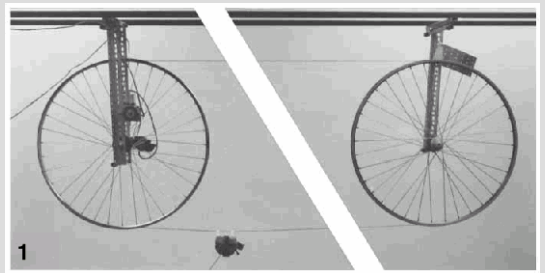
dopplershift
1. physics

doppler-shift
moving sound sources

$$f = f_0 / (1 + v/c)$$

c: 330 m/s in air

Dopplershift
2. Experiment



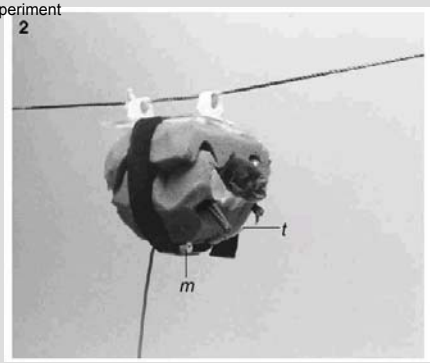
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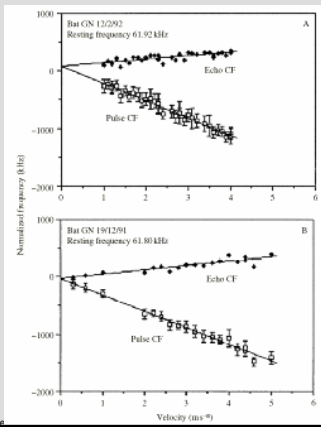
Dopplershift
3. Experiment
2

Bat holder

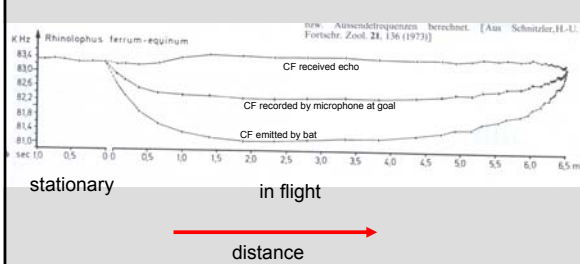


Dopplershift
4. data

yes, bats do
doppler shift compensation



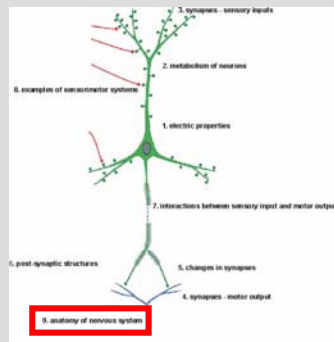
Dopplershift
5. more data



Summary:

- more examples for sensorimotor integration:
- whisker system in seals
- electric fish (adjustable reference copy)
- bats, compensation for doppler shift

9. anatomy of nervous system

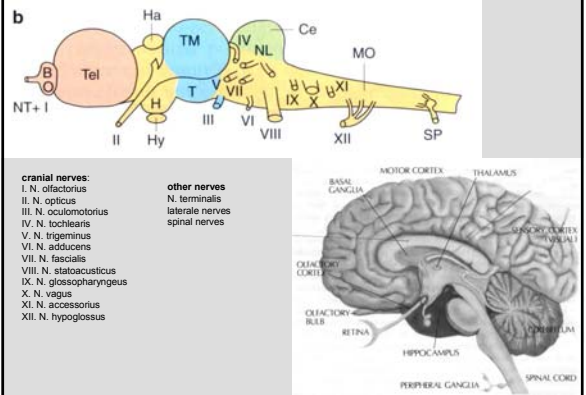


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standard brain



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Summary:

standard vertebrate brain: five sections,
12 cranial nerves

what is the take home message of all four lectures:

neurobiology is sometimes simply,
unfortunately often complicated,
but definitively thrilling!

For further discussion do not hesitate to contact:
uwe.ilg@uni.tuebingen.de

script will be available by FTP from
IP address: 134.2.99.9
user: guenne03

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